

Feature importance for software development effort estimation using multi level ensemble approaches

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ABSTRACT

Feature importance strategy that substantially impacts software development effort estimation (SDEE) can help lower the dimensionality of dataset size. SDEE models developed to estimate effort, time, and wealth required to accomplish a software product on a limited budget are used more frequently by project managers as decision-support tool effort estimation algorithms trained on a dataset containing essential elements to improve their estimation accuracy. Earlier research worked on creating and testing various estimation methods to get accurate. On the other hand, ensemble produces superior prediction accuracy than single approaches. Therefore, this study aims to identify, develop, and deploy an ensemble approach feasible and practical for forecasting software development activities with limited time and minimum effort. This paper proposed a collaborative system containing a multi-level ensemble approach. The first level grabs the optimal features by adopting boosting techniques that impact the decided target; this subset features forward to the second level developed by a stacked ensemble to compute the product development effort concerning lines of code (LOC) and actual. The proposed model yields high accuracy and is more accurate than distinct models.

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1. INTRODUCTION

One of the most significant tasks in the software industry is to develop a quality software product with minimal components depending on how accurately it estimates software development effort [1]. The challenge is evaluating those metrics early in the project lifecycle when each effort's limits must be determined, and there are significant uncertainties about the end product's functionality. It was defined as "estimating the effort and time required to develop a software product. The accuracy of its effort estimates primarily determines the success of any software product. Kumar *et al.* [2] demonstrates that the reasons for a software product failure are idealistic or inarticulate project goals, erroneous resource estimates, and inability to handle product difficulty. Perfect effort estimates are critical for project success. In papers [3]–[5] defines a reasonable estimation as providing a clear enough view of the product reality to allow project management to make sound decisions about overseeing the product to meet its objectives.

Software effort estimating (SEE) approaches of various types have been presented [6]. Among the suggested techniques, machine learning (ML) based effort estimators such as support vector machines (SVM), decision tree function (DTF) networks, and random forest trees (RFTs) have drawn more attention [7]. Making

no or few assumptions about the function being modelled and the training data is the driving force behind deploying such techniques. Such methods are preferred since they don't or lightly assume things about the modelled function and the training data. For instance, Rao and Rao [8] demonstrated that ensemble techniques outperform single classification models in SEE because the voting classifier in the ensemble model reduces any residual effect related to feature insignificance and redundancy. To mitigate this, higher weights are given to specific classifiers that excel on the tested datasets. The prediction performance is undoubtedly improved by the robustness of irrelevant and redundant features. In its simplest form of averaging, the voting model assures the reduction of noise property, which improves the overall prediction performance.

This paper proposes a multilevel ensemble (MLE) learning module for the software development effort estimation method. The proposed MLE system incorporates adaptive boost gradient tree boost in the first level and uses seven individual classifiers in the second, including the proposed stacked ensemble. The research sequel states that the base classifiers have been chosen following thorough simulation validation. Some of these classifiers, including the RF and SVM models, are considered in the literature [8]. The basis classifiers' diverse classification abilities also allow them to distinguish between various statistical properties of the underlying data, which adds value to the proposed ensemble learning approach.

The proposed ensemble model needs effective feature selection models to perform better overall. The enhancement's final effects will determine how well the redundant and unnecessary features in software product datasets are handled. This research aims to show how feature selection improves effort estimation performance and suggest a multilevel ensemble learning technique that is resistant to data imbalance and feature redundancy. The proposed multilevel ensemble technique has additionally demonstrated enhanced resistance to redundant and irrelevant characteristics, substantially contributing to this research. This research aims to show how feature importance improves effort estimation and suggests a multilevel ensemble learning technique resistant to feature redundancy and data imbalance. Another significant contribution credited to this research is the improved robustness of the suggested MLE to redundant and irrelevant information.

This paper has contained two innovative discoveries. Section 2 describes the literature-related research on the estimation methods for software development effort estimation. The ML models neural networks (NN 30-30), linear regression (LR), k-nearest neighbor (K-NN), SVM radial basis function (SVM RBF), naive bayes (NB), SVM polynomial (SVM poly), have to consider combining some of the best features of the suggested method are discussed with experimental setup in section 3, proposed multilevel ensemble learning model and summarizes the results of the studies and demonstrates the experimental design in section 4. The research is concluded in section 5, along with its future scope.

2. RELATED WORK

This section describes a summary of ML strategies offered after a study of general effort estimation algorithms, concludes with a review of various classification methods and methodologies, as well as a comparison of ways that can be used to estimate software development effort.

2.1. Single classifier for software development effort estimation

Quality development has evolved into a critical activity for professional companies. Indeed, developed software's prominence, cost, and suitability are frequently decisive elements in an organization's success. The complete analysis of ML techniques used for effort estimation was carried out by [9]. According to researchers' analyzed work, the researchers mainly focused on customizing specific algorithms, particularly artificial neural networks, case-based reasoning models, and decision trees, for the most outstanding performance. The machine's precision with mean magnitude relative errors (MMRE) ranging from 35 to 55%, percentage close error deviations (PRED(25)) of 47 to 75%, and median magnitude relative errors (MdMRE) of 30 to 55%, learning models were of an acceptable level and outperformed statistical ones. According to the researchers, ML algorithms may produce disparate findings due to outliers, missing variables, and the chance of over fitting problems. To estimate the early stages of the software life cycle initiatives, LR, and NN [10]. Shahpar *et al.* [11] investigated several data sets and obtained encouraging findings for software development effort assessment. When estimating software maintenance effort using particle swarm optimization, Singh *et al.* [12] proposed a successful swarm intelligence-based method. Regardless of the approach used to develop ML, valuable recommendations for effort and duration estimation at early project stages can be retrieved. Because ML is sensitive to noise in data sets, models should not rely on unique algorithms but should be employed in tandem, which improves prediction accuracy [13]. Boosting, bagging, and complex random sampling techniques [14] were proposed by researchers, generally for the same sort of ML algorithms. However, if used excessively, ensemble methods can cause significant performance overhead [15]. As a result, for developing ML effort and duration models, a limited selection of algorithms and a simple ensemble method, such as averaging of acquired estimates, should be employed.

2.2. Evolutionary strategy

A hybrid method to estimate work using the use case point methodology has been put out by [16]. Numerous observations were made based on college student projects and industrial projects. The authors of this paper gave the environmental elements of the UCP approach significant weight. The researchers used feed-forward algorithms like radial basis feed forward neural (RBFNN) to predict the effort and productivity feed-forward algorithm. This project concluded that the UCP method's environmental considerations are ideal for software system productivity forecasting.

More recently, [17]–[19] examined the application of learning machine ensembles for SEE. Ensembles of learning machines are groups of learners trained to complete the same job and are put together to enhance prediction performance [8]. It is generally accepted that learners should act differently when combined to obtain more accurate predictions. Otherwise, the total forecast won't be more accurate than the individual guesses. Therefore, several ensemble learning strategies can be viewed as various ways to create variation among the base learners. The authors tried to estimate effort with a low failure ratio and cost.

None of the publications compares the outcomes of other easily accessible methods for ensemble learning from the ML literature and the issues raised above. Researchers in [20], [21] provide data from a few ensemble approaches. However, the research does not statistically compare these methods and single learners. Different ensemble approaches can be more or less suitable for SEE and should be included in the comparisons. The papers also need to examine how the results were obtained.

2.3. Other approaches

According to particular research in the literature, the properties of the data set substantially impact how well various models perform. However, as previously indicated, existing research on ensemble models suggests that they perform better than distinct models even when numerous different data sets are employed. The results of the research methods, as presented in Table 1 (in Appendix) [18], [22]–[40] demonstrated that the optimal and significantly improved SDEE estimate performance was obtained by combining their two strategies. According to their projections, hybrid approaches may produce satisfactory results for varying sizes.

3. RESEARCH METHODOLOGY

This proposed research includes MLE approach to grab the optimal features as a precise step in the first level approach for choosing SDEE models to calculate effort in level 2. Figure 1 shows the overall feature selection process and software development effort estimation. The suggested method efficiently assigns ranks for features while simultaneously dealing with the imbalanced data problem in a software quality dataset to avoid bias problems. The following feature selection phases are defined to meet the objective.

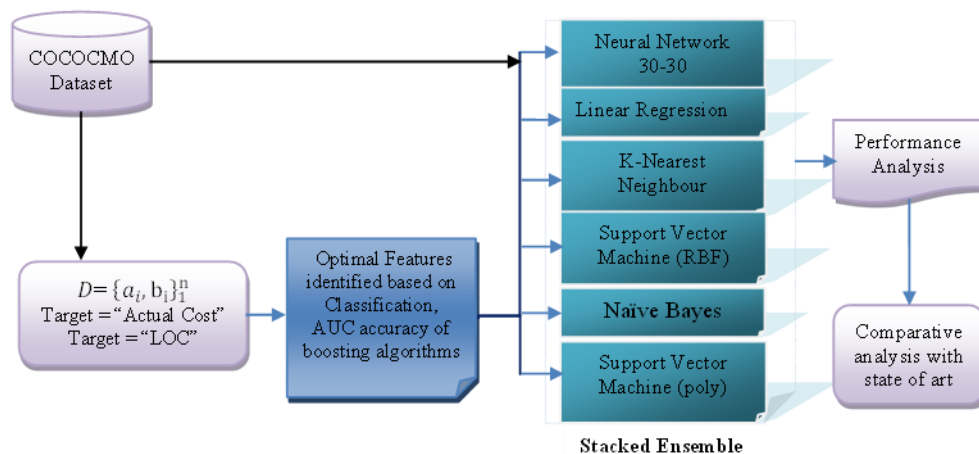


Figure 1. Prediction of SDEE using proposed MLE

3.1. Feature subset selection

A compelling feature selection system requires finding the primitive features that will be used to train the models [41]. The relevance or correlation between the characteristic and the class label serves as the

selection process's core guiding principle and is frequently applied to classification problems. Relevance measurements can be used to assess the significance of qualities like dimensionality reduction with five cross-fold validations. The model seeks to identify the best feature subset $\hat{f} (|f|) = k$ that maximises classification accuracy for a given dataset $D=(a_i, b_i)$, using a feature set and class label b . To this, we proposed an adaptive boosting [42] and gradient tree boosting [43] ensemble model that takes into account the base ensemble classifiers trained using classification and AUC accuracy of each feature and increased to three permutations produced by feature selection is known as ensemble feature selection aims to limit the impact of high dimensions on learning algorithms while conducting classifier accuracy and developing successful ensemble learning systems for classification difficulties.

The general process of ensemble feature selection is shown in Figure 1. The fundamental concept is to use loss (Ψ) of accuracy as shown in (1) of individual feature weight based on the feature subset is divided randomly and diversity across the chosen feature subsets is ensured, and finally the mean of all loss of all classification methods has been computed based on (2) to perform consistently and how effectively each single feature separates the given dataset $D=(a_i, b_i)$ to all 15 features they can distinguish between examples of proposed classifier models.

$$\Psi_{a_i}^{m_i} = ab(m_j.accuracy(D) - m_j.accuracy(D - a_i)) \quad (1)$$

In (1) Ψ represents loss of boosting model on each attribute a_i and $m_j.accuracy(D)$ denotes accuracy measure of boosting model m_i .

$$mean_{loss}^{a_i} = \sum_{f=1}^N ls_{a_i}^{m_i} \quad (2)$$

The proposed approach has two ensemble methods, in this approach both ensembles choose the correct class label, resulting in the correct conclusion have assigned a class label to each unique occurrence of the dataset, and the final class label is selected by a frequently occurrence in both methods as optimal. To support the first phase, the following algorithms 1 and 2 are taken.

Algorithm 1. Pseudo code of Ada-Boost for feature selection

Input:

Training Dataset $D=\{a_i, b_i\}_1^n$ where $a_i \in R^p$ and $b_i \in \{-1, +1\}$
Set of α features $F_e = \{a_1, a_2, \dots, a_\alpha\}$

Output:

Optimal features based on ranks $R = (D, \{r_{a_1}, r_{a_2} \dots r_{a_\alpha}\})$

Begin :

- 1: Initialize weights $w_{1,i} = \frac{1}{2m}, \frac{1}{2l}$ for $b_i = 0, 1$ respectively, for $k = 1, 2, \dots, K$
 - 2: Normalize weights $w_{k,i} = \frac{w_{k,i}}{\sum_{j=1}^n w_{k,j}}$
 - 3: Each feature j train a base classifier h_j which is classified to using a distinct feature.
 - 4: Calculate error w_k $\epsilon_k = \sum_i w_i |h_j(a_i) - b_i|$
 - 5: opt the classifier h_j , with the lowest error ϵ_k
 - 6: revise weights $w_{k+1,i} = w_{k,i} \beta_k^{1-x_i}$
 - 7: Repeat until weights upto get final $h(x) = \begin{cases} 1 & \sum_{k=1}^K \alpha_k h_k(a) \geq \frac{1}{2} \sum_{k=1}^K \alpha_k \\ 0 & \text{otherwise} \end{cases}$
where $\alpha_k = \log \frac{1}{\beta_k}$
 - 8: **end for**
The resulting model outputs are used as the final forecast for test cases.
- Note:** Ranking assigned from 1 to 10.

End

Algorithm 2. Pseudo code of gradient boost feature selection

Input:

Training Set $D=\{a_i, b_i\}_1^n$ where $a_i \in R^p$ and $b_i \in \{0, 1\}$
Set of α features $F_e = \{a_1, a_2, \dots, a_\alpha\}$

Output:

To assign rankings of features $R = (D, \{r_{a_1}, r_{a_2} \dots r_{a_\alpha}\})$

Begin :

- 1: $\{h_1, h_2, \dots, h_m\} \leftarrow \text{train GBT}$
- 2: $\hat{f} \leftarrow [0, \dots, 0]$
- 3: **for each** h_m **in** $\{h_1, h_2, \dots, h_m\}$ **do**
- 4: **for** $j = 1$ **to** d **do**
- 5: $\hat{f}_j = \hat{f}_j + \frac{1}{m} \cdot I_j(h_m)$

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6:  $\hat{I} \leftarrow \frac{i}{\sum_{j=1}^m I_j}$ 
7: for  $i = 1$  to  $n$  do
8:    $a_{i,j} \leftarrow [\hat{I}_j a_{i,j}]_{I_j \geq th}$  where threshold  $th \in (0,1)$ 
9: Return  $\{(a_1(i), b_i), i = 1, 2, \dots, n\}$ 
10: The dataset  $D$  is returned preserving only the selected features
    The resulting model outputs features importance according to weights.
    Note: Ranking assigned from 1 to 10.

```

End

To reach the proposed approach, this research used the COCOMO-81 dataset, as shown in Table 2, which accomplishes the selection of weighted features by rating their classification accuracy and AUC value in an initial model that includes all predictors. The gradient tree boost model uses a greedy optimisation strategy to identify the top-performing subset of elements based on the proposed Ada-Boost [35]. The dataset in Table 2 contains 17 features from F_1 to F_{15} as contributing, and the dependent as "LOC," in F_{16} and F_{17} as another target was "actual cost".

Table 2. Dataset information for COCOMO-81

| Feature. No. | Description of feature | Code | Value | GT Boost | | Ada-Boost | |
|-----------------|--------------------------------|--------|---------|-----------|----------|------------|------------|
| | | | | Mean | Std | Mean | Std |
| F_1 | Required software reliability | rely | Numeric | 0.01131 | 0.002986 | 0.00267857 | 0.00087617 |
| F_2 | Data base size | data | | 0.027381 | 0.002393 | 0.100645 | 0.0172055 |
| F_3 | Process complexity | cplx | | 0.001091 | 0.000982 | 0.0168651 | 0.00505271 |
| F_4 | Time constraint for cpu modern | time | | 0.009921 | 0.00271 | 0.126438 | 0.0119631 |
| F_5 | Main memory constraint | stor | | 0.00377 | 0.001964 | 0.0274802 | 0.0165147 |
| F_6 | Machine volatility | virt | | 0.000794 | 0.00014 | 0.00124008 | 0.00059936 |
| F_7 | Turnaround time | turn | | 0.003373 | 0.000612 | 0.00763889 | 0.00092 |
| F_8 | Analysts capability | acap | | 0.001687 | 0.001148 | 0.003125 | 0.00107994 |
| F_9 | Application experience | aexp | | 0.028373 | 0.00231 | 0.0198413 | 0.00546806 |
| F_{10} | Programmers capability | pcap | | 0.002679 | 0.000643 | 0.00128968 | 0.00101171 |
| F_{11} | Virtual machine experience | vexp | | -9.92E-05 | 0.00014 | 1.98E-04 | 0.0001403 |
| F_{12} | Language experience | lexp | | 0.000198 | 0.00014 | 0.0014881 | 0.00084179 |
| F_{13} | Programming practices | modp | | 0.000595 | 0.000643 | 0.018502 | 0.00633835 |
| F_{14} | Use of software tools | tool | | 0.001984 | 0.000982 | 0.00138889 | 0.0002806 |
| F_{15} | Schedule constraint | sced | | 0.000496 | 0.000506 | 0.00530754 | 0.00401939 |
| F_{16} | Target Lines of code | LOC | Actual | | | | |
| F_{17} | Actual cost | Actual | | | | | |

From the above, collected sufficient number of features based on their ranks with respect to two targets. Then these sets of data forwarded to seven classifiers and calculate the loss Ψ of each one as shown in (3):

$$\Psi_{M_i}^{M_n} = ab(M_n, \text{acc}(T_r)) \quad (3)$$

Where $mean_{loss}^{a_i}$ calculates mean loss of each permutation to three permutations for all individual classifiers. When working on a specific learning set, the stacked model can be thought of as a method of calculating all base classifier losses $\sum_{i=1}^N \Psi$ and then correcting prediction residuals using the level 1 model. The mean of all accuracy losses is derived using (5), which stands for the mean of all accuracy losses.

$$\text{Mean}_{\Psi}^{M_n} = \sum_{j=1}^N \Psi_{M_i}^{M_n} \quad (4)$$

In (4), $\Psi_{M_i}^{M_n}$ represents the loss of classifier M_n on selected feature f_i and $M_n, \text{acc}(T_r)$ denotes accuracy measure of classifier M_n . In (4), $\text{Mean}_{\Psi}^{M_n}$ represents mean loss upon ranked features M_i from all classifiers. The overall accuracy is produced in the order that optimal features are selected based on the ranking. The ensemble classifier was used to choose and consider the top features for inclusion in the classification model based on the output of the ranked features that were analyzed.

3.2. Experimental setup and simulation

The proposed research was executed on a system which contains Intel(R) i5 – 6200 CPU 3.40 GHz, 8 GB (RAM), and a 64-bit latest Windows-10 (OS) GUI interface. Python Anaconda is an open-source programming language, and Spyder IDE is used for the simulation. Table 3, all the classifiers' parameters are selected using a trial-error method.

Table 3. Parameter setup

| Base models | Parameter setup |
|---------------------------------|---|
| KNN | {Number of neighbours (k): 5} |
| Naïve bayes | {No hyperparameters to tune } |
| SVM poly | {C (regularization parameter): 1.0}; {kernel: polynomial}; {degree of polynomial kernel: 3} |
| SVM RBF | {C (regularization parameter): 1.0}; {kernel: RBF} |
| NN 30-30 | {Neurons per layer: 30}; {activation function: relu for hidden} |
| | {layers, softmax for output layer}; {learning rate: 0.001}; {training duration: 100 epochs} |
| LR | {Regularization type: l2 (ridge)}; {regularization parameter (c): 1.0} |
| | {training duration: 100 epochs} |
| Proposed stacked ensemble model | {Base models: nn 3030 classifier, SVM RBF, NB, SVM poly, LR} |
| | {Meta learner: logistic regression} |
| | {Number of base models: 6} |
| | {Hyperparameters for base models and meta learner tuned during stacking} |

4. RESULT ANALYSIS

As stated in the first phase results in Table 2, using two boosting models, optimal features were identified, and ranks were assigned. Those two models gave good recognition to the elements in standard, prepared an optimal dataset with the optimal ranked features, and then calculated mean loss and rank. Figure 2 shows an analysis of the optimal dataset with ten features assigned positions for each element by applying GT Boosting classification accuracy (CA) and AUC score. Figure 3 represents classifier accuracy and AUC of the Ada-Boost classifier of optimal features. Calculated ranks for top ten features with the support of Ada-Boost classifier. Here, we can observe the positions for the top ten out of fifteen parameters based on their scores.

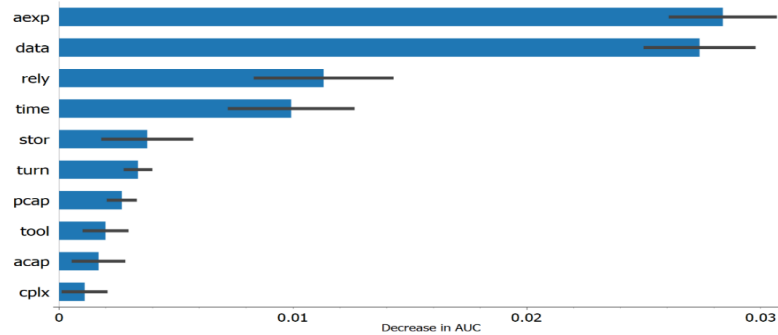


Figure 2. Gradient tree boosting classifier feature ranking

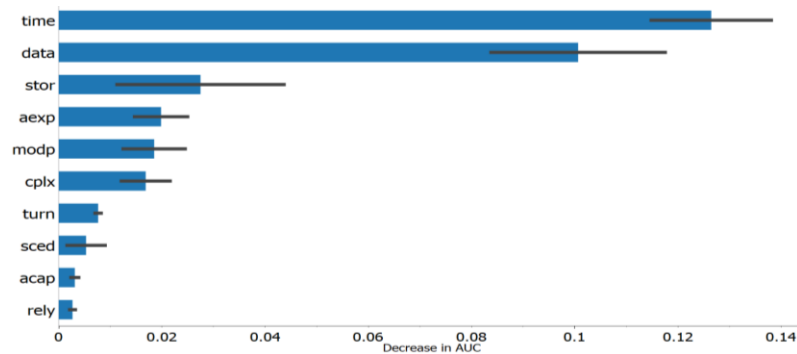


Figure 3. Ada-Boosting classifier feature ranking

According to algorithms 1 and 2, calculate CA and AUC scores each boosting algorithm assigns ranks as shown in Table 4. Positions are given to all fifteen features such as F_{rely} , F_{data} , F_{cplx} , F_{time} , F_{stor} , F_{virt} , F_{turn} , F_{acap} , F_{aexp} , F_{pcap} , F_{vexp} , F_{lexp} , F_{modp} , F_{tool} , F_{sced} . Out of fifteen features GT Boosting CA is very low for F_{virt} , F_{vexp} , F_{lexp} , F_{modp} , F_{sced} features, and Ada-Boost CA is very low F_{virt} , F_{pcap} , F_{vexp} , F_{lexp} , F_{tool} . So, which features are commonly identified and get low accuracies for both

algorithms are removed from the original dataset and a new subset of features with twelve features and this subset of features dataset forward to next level ensemble approach.

Table 4. Rankings of features for predicting boosting classifiers

| Optimal features based on their ranks | |
|--|---|
| Adaptive boost classifier | GT boost classifier |
| $[F_1, F_8, F_{15}, F_7, F_3, F_{13}, F_9, F_5, F_2, F_4]$ required software reliability (rely), analysts capability (acap), schedule constraint (sced), turnaround time (turn), process complexity (cplx), programming practices (modp), application experience (aexp), data base size (data), main memory constraint (stor), time constraint for cpu modern (time). | $[F_3, F_8, F_{14}, F_{10}, F_7, F_5, F_9, F_4, F_1, F_2]$ process complexity (cplx), analysts capability (acap), programmers capability (pcap), use of software tools (tool), turnaround time (turn), main memory constraint (stor), application experience (aexp), required software reliability (rely), data base size (data), time constraint for cpu modern (time). |
| New optimal subset features total 12 | $[F_1, F_2, F_3, F_4, F_5, F_7, F_8, F_9, F_{10}, F_{13}, F_{14}, F_{15}]$ |

4.1. Discussion on level 1 results

As per MLE proposed model the first level conducting experiments for the original dataset and the performance metrics of all six classifiers (NN 30-30, NB, SVM RBF, SVM poly, K-NN, and LR) concerning the LOC and actual cost as targets reside in the original dataset, based on the experiments calculate the CA, AUC, F1, precision and recall to all classifiers and outcomes showed in Table 5 for each model. All models have shown relatively good performance in predicting the performance metrics. NB scored 97%, and K-NN scored 99%, indeed a better performance compared to all other models, as the process's objective was to predict the actual effort and LOC in the target dataset for developing the SDEE. SVM poly stands good in CA with 95% precision and a low error rate, and the NN 30-30 classifier stands at an accuracy of 54% on other models to predict targets.

Table 5. Classifiers performance was observed with 15 features

| S.No | Base model | Performance measures with 15 features | | | | |
|------|---------------------|---------------------------------------|-------|----------|-----------|--------|
| | | AUC | CA | F1-score | Precision | Recall |
| 1. | NN 30-30 classifier | 0.831 | 0.476 | 0.438 | 0.545 | 0.476 |
| 2. | NB | 0.973 | 0.667 | 0.694 | 0.846 | 0.667 |
| 3. | SVM RBF | 0.541 | 0.825 | 0.833 | 0.851 | 0.825 |
| 4. | K-NN (EQU) | 0.993 | 0.873 | 0.870 | 0.883 | 0.873 |
| 5. | SVM poly | 0.651 | 0.937 | 0.939 | 0.955 | 0.937 |
| 6. | LR | 0.906 | 0.873 | 0.873 | 0.908 | 0.873 |

The ROC-AUC curve in Figure 4 shows the relationship between the true positive rate (TPR), which measures the model sensitivity and the false positive rate (FPR) which measures model specificity for the original dataset, which participates in fifteen features and finds the targets as LOC and actual cost, both are proportional.

According to the ROC curve, NB performs better than the remaining individual classifiers, all indicating respective colours, as shown in Figure 4. A lift curve analysis helps evaluate the performance of different models, especially in classification tasks. Figure 5 shows the K-NN model achieves an exceptionally high AUC of 4.65 at a probability threshold of 0.0, indicating that it can make highly accurate predictions when selecting the nearest neighbors. The SVM model with a polynomial kernel has a lower AUC of 0.508 at a probability threshold 0.168. This suggests that it may not perform as well.

4.2. Discussion on stacking ensemble learning approach at level 2

Based on the research proposal in the second level, we used an effective ensemble learning algorithm that learns how to combine predictions from two or more base ML techniques, the stacked ensemble. It is used to train models and make predictions, and the advantage of stacking is that it can combine the abilities of six high-performing models on a classification and regression difficulties task to provide forecasts that perform better than any one model in the ensemble [44]. Using this method, the performances of multiple models are integrated to create a single, effectual output. This method uses level 1 as a base model fitting to the training data and whose predictions are generated and level 2 as a meta-model that learns how to best combine the base models' predictions. The results of the fundamental learners' developing features can be integrated using a weighted average. It grants the model dominance in prediction performance as well as reliability. Also, the high-impact features selected by RF and GTB can be seen in Table 4, with the optimal subset of features a new featured dataset prepared separately and given as input to

all classifiers, including proposed stacked ensemble and conduct experiments. For this experiment, actual cost and LOC are the target variables (both are proportional) to find the performance of the proposed model, including all the model's accuracies, as shown in Table 6. The model performance evaluation used the same metrics followed by level 1. The evaluation mechanism used in this study focuses on assessing the performance of the new optimal feature dataset in predicting the development effort.

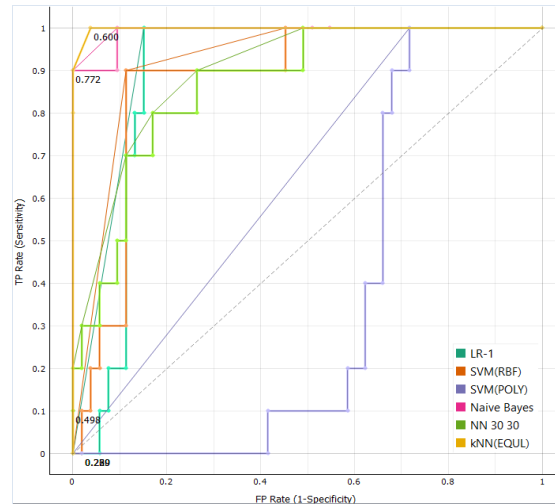


Figure 4. Performance of all models on fifteen features

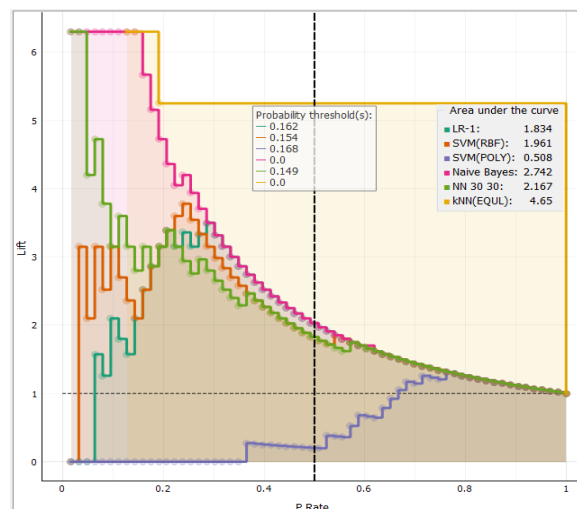


Figure 5. Lift curve of all models on original dataset

Table 6. Performance of ensemble model in comparison to that of classifiers for optimal features

| S.No | Base model | Performance measures with 12 features | | | | |
|------|---------------------|---------------------------------------|-------|----------|-----------|--------|
| | | AUC | CA | F1-score | Precision | Recall |
| 1. | NN 30-30 classifier | 0.841 | 0.492 | 0.481 | 0.580 | 0.492 |
| 2. | Navie bayes | 0.977 | 0.667 | 0.692 | 0.781 | 0.667 |
| 3. | SVM RBF | 0.606 | 0.810 | 0.812 | 0.833 | 0.810 |
| 4. | K-NN (EQUL) | 0.983 | 0.873 | 0.870 | 0.883 | 0.873 |
| 5. | SVM poly | 0.965 | 0.921 | 0.925 | 0.947 | 0.921 |
| 6. | LR | 0.851 | 0.794 | 0.791 | 0.807 | 0.794 |
| 7. | Stacked ensemble | 0.989 | 0.990 | 0.990 | 0.991 | 0.996 |

After an experimental study with a proposed model conducting experiments with twelve features, all classifiers have shown good performance compared with level 1 results in predicting the performance metrics. The outcome of our research proposal stacked ensemble scored 99%, and K-NN scored 98%, indeed a better performance compared to all other models, as the objective of the process was to predict the actual

effort and LOC in the target dataset for developing the SDEE. The proposed stacked ensemble stands at 99% in CA, 99% precision and less error to predict the target.

The ROC-AUC curve in Figure 6 shows the relationship between TPR, which measures the model sensitivity, and FPR, which measures model specificity for the optimal feature subset of the dataset which participates in twelve features and finds the targets as LOC and actual cost, (both are proportional). According to the ROC curve, the proposed stacked ensemble reached 1 to perform all-time better than all remaining individual classifiers, all indicating respective colours, as shown in Figure 6.

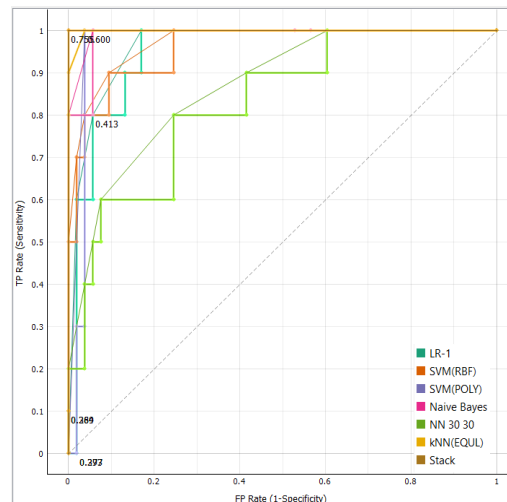


Figure 6. Performance of all models on optimal feature subset dataset

The probability of the threshold of the proposed stacked ensemble classifier for the optimal feature subset dataset (12 features) was also calculated to find the error in each effort category. Figure 7 shows the lift curve analysis for each model, including the stacked ensemble concerning LOC and Actual as targets. The proposed model achieves an exceptionally high AUC of 2.783 at a probability threshold of 0.025, indicating that it can make highly accurate predictions compared to other individual models. The proposed model has a lower high AUC at a probability threshold 0.0258. This suggests that our proposed model performs well, indicating that it can make highly accurate predictions comparatively with the state-of-the-art models.

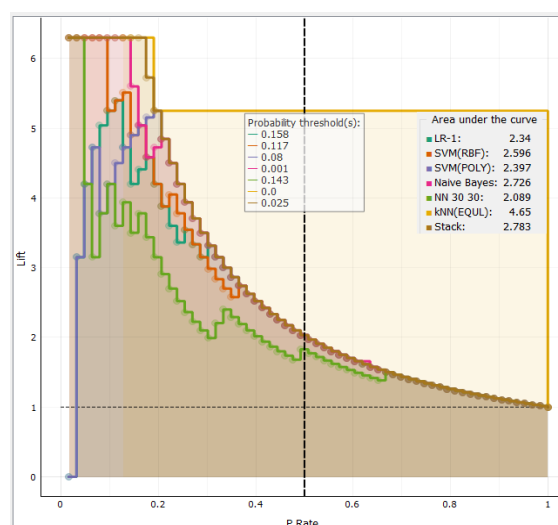


Figure 7. Lift curve of all models on optimal feature subset dataset

Compared to the feature ranking technique, the accuracy obtained by stacked ensemble learning for all classifiers as shown in Table 6 has been impressively promising. This is partly due to the stacked ensemble-learning algorithm's dedicated targeting of the top features based on ranking. Compared to the ideal dataset, Figure 8 displays the classification accuracy and AUC values for the base learners and the proposed stacked ensemble approach. The proposed stacking ensemble produced the all-time highest accuracy in predicting SDEE and proves this research study's objective.

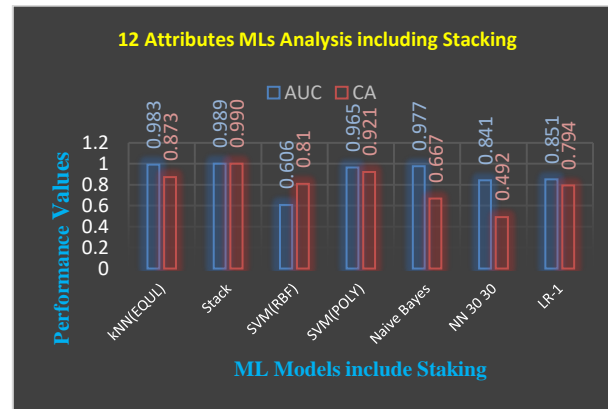


Figure 8. Model analysis of proposed model on optimal feature subset dataset

5. CONCLUSION

This research examined ways to estimate the software development effort with minimum time. We noticed that using a few outstanding features yields a considerably greater AUC than the alternative. In addition, NB and K-NN outperformed comparative with traditional techniques like NN 30-30, SVMs (poly, RBF), and LR on the COCOMO dataset, and we proved that they usually incorporate more essential features in achieving an acceptable level of accuracy and indicating that giving features weights may improve SDEE when employing individual classifiers. For this, we propose a multi-level ensemble model to predict outstanding features based on priority to estimate development effort by adopting a stacked ensemble with a group of six well-designed learners, which outperformed and higher AUC measurements over the more traditional techniques like NN 30-30, SVMs (poly, RBF), NB, K-NN, and LR. Based on the No Free Lunch theorem, according to “No Free Lunch hypothesis” No-one ML classifier model is the best on every situation, so when taking into account different ensembles, our work has revealed that it is improbable that there is a model that is always the best. The software product manager should ideally test several models while employing a guiding framework considering all the goals and projects they access. It makes it possible to pinpoint the model to deliver the behaviour that best suits the manager's requirements. In future, we plan to use further feature selection approaches to support our claim that many features in publicly available software product datasets are unnecessary or redundant. Investigating additional ensemble learners to contrast our system will also be part of future work.

APPENDIX

Table 1. Research on software effort estimation by adopting various approaches

| S.No | Techniques used | Data-set used | Problem name | State of art | Metrics used for study | Ref. |
|------|-----------------|---------------|------------------------------|--------------|------------------------|------|
| 1. | RSA | USP05-FT | Feature reduction | FFNN | – MMRE | [22] |
| | | USP05-RQ | | NB | – RMSE | |
| | | | | | – MAE | |
| 2. | DTF | ISBSG | SEE | DT | – MRE | [23] |
| | | Desharnais | | MLR | – MMRE | |
| | | | | | – MdMRE | |
| 3. | COCOMO | NASA 93 | SDEE | NB | – PRED | [24] |
| | | | | LR | – AUC | |
| | | | | RF | – CA | |
| 4. | ANN | COCOMO II | Minimize predetermined error | - | – Precision | [25] |
| | | | | | – Recall | |
| | | | | | – MMRE | |
| | | | | | – MSE | |

Table 1. Research on software effort estimation by adopting various appraochs (*continued*)

| S.No | Techniques used | Data-set used | Problem name | State of art | Metrics used for study | Ref. |
|------|---|--|---------------------------------------|-----------------------------------|---|------|
| 5. | GLM | ISBSG | SEE | SVM MLP | – MAE – RMSE – MMER, etc | [26] |
| 6. | RF | ISBSG COCOMO | SEE | - | – PRED – MRE – MMRE – PRED | [18] |
| 7. | GA, PSO, FL, ACO, ABC | - | Predict reliability | - | - | [27] |
| 8. | SEER-SEM | COCOMO | FPA | - | – MMRE – PRED | [28] |
| 9. | OLS SWR RR | COCOMO MAXWELL CHINA | Regression based effort estimation | ML | – MAE – BMMRE | [29] |
| 10. | ABEO-KN | Promise Repository datasets | Ranking of estimation methods | Analog based methods | – MMRE – MAR – MdAR – SD – RSD – LSD | [30] |
| 11. | ASEE | Desharnais ISBSG Albrecht COCOMO Kemerer | SDEE | Analog based SDEE | – MMRE – PRED – MdMRE – MRE | [31] |
| 12. | ANN | COCOMO | Estimating effort | - | – MMRE – PRED – RMSE | [32] |
| 13. | Classical analogy Ensemble | ISBSG | SEE | Fuzzy analogy models | – MAE – LSD – MBRE – MIBRE | [33] |
| 14. | GP, MOGP | Desharnais, Finnish Miyazaki | Accuracy | - | – MMRE – PRED – MdEMRE | [34] |
| 15. | Multi layered feed forward neural network (MLFFANN) | COCOMOII | Prediction of software effort | - | – MSE – MMRE | [35] |
| 16. | Fuzzy logic | - | SCE | Bailey Basili, Dotly, Halstead | – MRE,MF – MMRE | [36] |
| 17. | ABE | ISBSG | Predict SEE | CART MLR CNN | – MRE – MMRE – PRED | [37] |
| 18. | Ada Boost | Desharnais MAXWELL | LOC, actual cost | K-NN SVM | – Loss – Accuracy | [38] |
| 19. | ML CBR | Infoway Diyatech Tsoft | SDE | - | – BRE – MRE | [39] |
| 20. | Metaheuristic optimization | NASA | | GA, PSO, FA | – MAE – MMRE – VAF | [40] |

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