Evaluating multi-state systems reliability with a new improved method

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ABSTRACT

The computation of network reliability for a system with many states is an NP-hard issue. Finding all the minimum path vectors (d-MPs) lower boundary points for each level d is one of the few approaches for computing such dependability. This research proposed enhancements to the technique described in Chen's "Searching for d-MPs with rapid enumeration" paper. We propose additional adjustments to the method that creates the flow vector F in this enhancement. This decreases the number of required steps and the temporal complexity of the method. Comparing the newly suggested approach to the old algorithm reveals that the adjustment has increased the enumeration's efficiency and degree of complexity.

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1. INTRODUCTION

The area of machine learning has exceeded the level of performance that can be achieved by humans on a variety of categorization problems with the emergence of deep learning. Concurrently, there is an urgent need to describe and measure the reliability of a model's prediction based on individual samples. This is particularly true when such models are used in the context of safety-critical areas [1]–[3].

The reliability theory aim is to compute the reliability of complex systems from the awareness of the reliabilities of its components. Various methods for computing system reliability have been introduced in the literature. Among these methods we can find cut/path set enumeration [4]–[13], the state enumeration methods [14], [15].

According to the traditional reliability theory, an element can only be in a functioning or failed condition [16]. However, portions of multi-state systems have varying capacity levels under a variety of circumstances. Concerning these systems, we compute the probability that the flow from the origin node towards the sink node is higher than or equal to the specified demand d [17], [18].

The enumeration of all d-minimal pathways (d-MPs) for a certain level d is one of the available approaches [10], [19]–[25] for computing the system dependability of a multi-state system. There are two ways provided in the literature for locating all d-MPs for a certain d. The first one generates d-MPs using direct methods, and the second approach generates d-MPs using pre-enumerated minimal paths (MPs).
Yeh [26] suggested a component-based formulation with three limitations to get d-MPs as one of the direct techniques that may generate d-MPs. The second is Ramirez [20], which proposed an additional way for information-sharing mechanisms.

Bai [22] introduced a novel approach that creates the d-MP candidates by merging all the MPs and determining if each d-MP candidate is less than the whole state vector. In [21], Lin offered a mathematical formulation based on three restrictions for obtaining the candidates for d-MPs from all previously enumerated MPs. Lamalem [25] presented a novel method for listing all d-MPs for all d levels. This method utilizes the network's routes matrix to generate new d-MP candidates from (d-1)-MP d-MP candidates. Chen [27] used a novel approach known as integer-programming [28] to reduce the number of steps required to generate the flow vector F.

Providing new improvements to the Chen [16] method, this study claimed new improvements. These adjustments reduce by a minimum of 60 times the number of steps necessary to get the flow vector F. To demonstrate the effectiveness of the suggested enhancements, we conducted several experiments and compared the results to a well-known method.

The remainder of the paper is structured as follows: The first part provides the method's definitions and underlying assumptions. The stochastic-flow network model is described in section 3. Next, in section 4, we present Chen’s algorithm [27] and Lin [21]. Later in section 5, we propose the new improvements to Chen’s [27] algorithm. In the end, The efficiency of the new improvements added to the algorithm is compared with Chen [27] and Lin [21].

2. METHODS
2.1. Definitions
For G(A, N, M) is the stochastic-flow network, such that A=(a₁, ..., aₙ) defines the group of edges, N=(n₁, ..., nₙ) defines the group of nodes, and M=(M₁, ..., Mₙ) defines the full capacity of each edge aᵢ.

The path is a group of elements that connect the sources s to the sink t. The Minimal Path (MP) is a path that contains no other paths between the source s and the terminal t.

2.2. Assumptions
The network should specify the fundamental following hypothesis:
- Each state of an arc is statistically independent of another arc.
- The nodes are working perfectly.
- The capacity of every element aᵢ ranges from 0<1<2...<Mᵢ.
- The network's flow conforms to the flow-conservation rule.

2.3. Model of stochastic network flow
Let p₁, p₂, ..., pₙ represent the collection of MPs from the source s to the terminal or sink t. The stochastic-flow networking may be represented by two vectors: the flow vector F=(f₁, f₂, ...fₙ) and the capacity vector X=(x₁, x₂, ..., xₙ), where fᵢ represents the overall flow of a MP. Moreover, pᵢ and xᵢ represents the current capacity of an edge aᵢ. The vector F is attainable if and only if the following conditions are met:

\[ \sum_{j=1}^{n} f_j \mid a_i \leq M_i, i=1, 2, ..., n \] (1)

\[ \sum_{j=1}^{n} f_j = d \] (2)

\[ f_j \leq \min \{M_i \mid a_i \leq p_j, j=1, 2, ..., m \} \] (3)

According to constraint (1), the total flow through aᵢ under F cannot exceed Mᵢ. Constraint (2), states that the entire flow of F equals the supplied demand d. The third constraint is that the flow on each MP pᵢ cannot exceed its maximum capacity. Lemma 1 Any F that fulfills restriction (1) satisfies restriction (3).

Proof 1: If the total of the flows of the several pathways crossing an edge is less than its capacity, then the flow of a specific path is less than the sum of the capacities of the many paths it crosses, indicating the smallest of them.

Let F=\{F — meets the conditions (1) and (2)\}. X=(x₁, x₂,..., xₙ) is a d-MPs capacity vector for a given d. If there exists an \( F \in \mathbb{F} \) such that:
\[ x_i = \sum_{j=1}^{\ell} \{ f_j \mid a_i \in p_j \}, i = 1, 2, ..., n \] (4)

Let \( \phi(X) \) represent the flow from node s to sink t, \( \phi(X) \) is the capacity or status of the system. Assuming there are \( L \) d-MPs, they are denoted by \( Z_1, Z_2, Z_3, ..., Z_L \). Therefore, the possibility that \( \phi(X) \geq d \) may be determined as follows:

\[ P_r(\phi(X)) = P_r((X \geq Z^1) \cup (X \geq Z^2) \cup ... \cup (X \geq Z^L)) \] (5)

Occurrence \( X \geq Z \) denotes \( x_i \geq z_i \) for each \( i \), where \( X \) and \( Z \) are identically sized vectors.

Based on a multistate network with \( n \) autonomous nodes. Component \( i \) (\( 1 \leq i \leq n \)) has \( M_i + 1 \) discrete and mutually exclusive states 0, 1, ..., \( M_i \). For a specific vector \( Z \) whose component \( z_i \) indicates the position of component \( i \), where:

\[ P_r(X \leq Z) = \prod_{i=0}^{n} P_r(x_i \geq z_i) \] (6)

2.4. Chen and Lin algorithmic improvements

To explain Chen’s process, we shall utilize Figure 1 from Chen [27] as a network. For locating all viable solutions to \( F = (f_1, f_2, ..., f_z) \), we must apply the constraints (1), (2) and (3).

![Figure 1. Graph taken from Chen](image)

In Figure 1, there are four minimum paths: \( p_1 = (a_1, a_3, a_6) \), \( p_2 = (a_2, a_4, a_7) \), \( p_3 = (a_2, a_5, a_6) \), and \( p_4 = (a_1, a_3, a_5, a_4, a_7) \). They correlate to corresponding \( F = (f_1, f_2, f_3, f_4) \), the provided requirement \( d \) is 5 and the full capacity for every arc \( a_i \) is 5.

From constraint (3), we have:

\[
\begin{align*}
  f_1 &\leq 5 \\
  f_2 &\leq 5 \\
  f_3 &\leq 5 \\
  f_4 &\leq 5
\end{align*}
\]

From constraint (1), we have:

\[
\begin{align*}
  f_1 + f_4 &\leq 5 \\
  f_2 + f_3 &\leq 5 \\
  f_2 + f_4 &\leq 5 \\
  f_3 + f_4 &\leq 5 \\
  f_1 + f_3 &\leq 5
\end{align*}
\]

From constraint (2), we have:

\[ f_1 + f_2 + f_2 + f_4 = 5 \]

The system of equations to be solved is:
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2.4.1. The conventional explicit statement

In [21], Lin’s program that utilizes explicit enumeration to explore $f_1, f_2, f_3, f_4$ is identical to the following code; it employs four loops, and in each loop, the flow $f_i$ begins at 0 and ends at minimum $\{M^i | a_i \in p_j, j = 1, 2, 3, ... m\}$ as a constraint (3).

As it can be noticed, Lin’s [21] algorithm enters each loop and stops at the last condition to check if it’s false or true. If the condition is satisfied, the algorithm adds the flows $(f_1, f_2, f_3, f_4)$ to the set of feasible solutions $F$. The computation complexity required by running this algorithm using the network of Figure 1 is $6*6*6*6 = 1296$ steps (because each flow $f_i$ start from 0 to 5).

2.4.2. Chen’s algorithm

Chen’s algorithm [27] employs the linear programming approach presented in [28]. The method reorders the constraints in order to decrease the number of required steps. Using the same example from Figure 1, the reorganizations result in:

\[
\begin{align*}
    & f_1 \leq 5, \\
    & f_2 \leq 5, \\
    & f_3 \leq 5, \\
    & f_4 \leq 5, \\
    & f_1 + f_4 \leq 5 \\
    & f_2 + f_4 \leq 5 \\
    & f_3 + f_4 \leq 5 \\
    & f_1 + f_3 \leq 5 \\
    & f_1 + f_2 + f_2 + f_4 = 5
\end{align*}
\]

This strategy of reordering the constraints allows the algorithm to add certain constraints after several iterations, which implies that the algorithm will not enter each iteration as Lin’s [21] algorithm does. This strategy used by Chen [28] will decrease the number of steps required to locate all potential answers $F$. 

\[
\begin{align*}
    & f_1 \leq 5, \\
    & f_2 \leq 5, \\
    & f_3 \leq 5, \\
    & f_4 \leq 5, \\
    & f_1 + f_4 \leq 5 \\
    & f_2 + f_4 \leq 5 \\
    & f_3 + f_4 \leq 5 \\
    & f_1 + f_3 \leq 5 \\
    & f_1 + f_2 + f_2 + f_4 = 5
\end{align*}
\]
Chen's approach [16] requires 546 steps, which is a significant decrease from 1296 to 546 steps by just reordering the requirements. This number can also be decreased by adding new improvements to the algorithm so it will need only 56 steps.

3. PROPOSED IMPROVEMENTS

3.1. Background

Chen’s [16] algorithm uses the integer programming problems presented in [28]. Despite that, the algorithm of Chen [16] didn’t take advantage of constraint (2), for all the F: $f_1$ begin from 0 to 5, $f_2$ begin from 0 to 5, and $f_3$ begin from 0 to 5, which increment the steps needed even with re-ordering the constraints. The purpose of the new enhancements is to appropriately apply constraint (2) to reduce the number of required steps.

The purpose of the new enhancements is to appropriately apply constraint (2) to reduce the number of required steps. Constraint (2) states that the entire flow must match the supplied demand $d$, meaning it cannot exceed $d$. Consider the following scenario with a demand of 5.

$$\begin{align*}
&\text{if } f_1 = 3, \text{ then } \\
&\text{if } f_2 = 2, \text{ then } \\
&\quad \text{if } f_3 = 2, \text{ then } \\
&\quad \quad \text{if } f_4 \leq 2 \text{ and } f_3 + f_4 \leq 5, \text{ then } \\
&\quad \quad \quad \text{if } f_2 \leq 2 \text{ and } f_3 + f_4 \leq 5, \text{ and } f_1 + f_2 + f_3 + f_4 = 5, \text{ then } \\
&\quad \quad \quad \quad \text{and } f_4 \leq 5, \text{ and } f_3 + f_4 \leq 5, \text{ and } f_1 + f_2 + f_3 + f_4 = 5, \text{ and } \text{true } \\
&\text{if } f_4 = 3, \text{ then } \\
&\text{if } f_3 = 2, \text{ then } \\
&\quad \text{if } f_2 = 2, \text{ then } \\
&\quad \quad \text{if } f_1 = 2, \text{ then } \\
&\quad \quad \quad \text{and } f_1 + f_2 + f_3 + f_4 = 5, \text{ and } \text{true } \\
&\quad \quad \quad \quad \text{and } f_1 + f_2 + f_3 + f_4 = 5, \text{ and } \text{false } \\
\end{align*}$$

By this example, we can deduce that the algorithm traversed all of the loops before reaching the constraint (2). The issue with this approach is that it enters branches that it is not meant to (i.e., we already have the relevant data to decide using constraint (2)). When $f_1 = 3$, the flow $f_4$ should only take values between 0 and 2, not 5, since if $f_4 = 4$, then $f_1 + f_4 = 7 > d$, indicating that the values taken by flow $f_4$ rely on the value of flow $f_3$. This example demonstrates that Chen's approach enters branches that cannot provide a solution for which we already have definitive knowledge.

The same applies to $f_3$, if $f_2$ takes 3 and $f_4$ takes 2, $f_1$ should take only 0 as value, because $f_1 + f_2 = d = 5$. The same thing for $f_2$. Consequently, the present flow values are dependent on the values of the prior flows. The suggested enhancements determine the current flow maximum capacity that cannot be exceeded by maximizing constraint (2), constraint (3), past flows, and demand $d$.

Let $L_j$ signify $\min \{M | \forall i \in p\}$.

Let $N \equiv \{F|F \text{ are preceding flows}\}$.

$$\begin{align*}
\text{Max } f_i = & \min(d - \left(\sum_{j \in \mathcal{N}} f_j \right), L_j) \\
\end{align*}$$

(7)

Max. $f_i$ is the maximum carrying capacity of the flow $f_i$.

The final variable after reordering the equations shall only take on a single value that satisfies the requirement (2). We use,

$$\sum_{j=1}^{z} f_j = d$$

(8)
Which implies:

\[ f_n = d - \sum_{j=1}^{n} f_j \]  

(9)

The last variable after reordering the equations is \( f_n \).

In (7) and (8) will decrease a significant number of steps, and the algorithm will only enter branches that potentially lead to a solution while avoiding time-wasting branches. The constraints derived from (3) will be replaced with constraints derived from (7). Consequently, if these alterations are taken into account, the resultant equation of constraint (2) will be substituted by the result of constraint (3) on the final variable.

Consider, for instance, the last loop of algorithm 2:

\begin{verbatim}
FOR \((f_2 = 0; f_2 \leq 5; f_2++)\) do
  \textbf{IF} \(f_2 + f_3 \leq 5\) and \(f_2 + f_4 \leq 5\) and \(f_1 + f_2 + f_3 + f_4 = 5\)
  \textbf{F} = \textbf{F} \cup \{F\}
ENDIF
ENDFOR
\end{verbatim}

The following will replace this loop:

\[ f_2 = 5 - f_1 + f_3 + f_4 \] //using (8).

\textbf{IF} \(f_2 + f_3 \leq 5\) and \(f_2 + f_4 \leq 5\) and \(f_2 \leq 5\)
\textbf{F} = \textbf{F} \cup \{F\}
ENDIF

3.2. Illustration

To clarify the new improvements, we took the example used by Chen and Lin. Taking the improvements given previously (section 5), before taking each flow \(f_i\), we compute the Max \(f_i\) that this flow cannot exceed to avoid many iterations. The new algorithm relating to Figure 1 is given in algorithm 3.

After applying the two proposed in (7) and (8) to the network in Figure 1, when \(f_1 = 3, f_4\) will take only the values from 0 to 2 instead of 0 to 5. Another example, when \(f_1 = 3, f_4 = 2, f_3\) will take only 0 as value instead the values from 0 to 5. As a result, the number of steps required to locate the flow vector \(F\) in this case is 56 instead of 546 of Chen’s [16] and 1296 of Lin’s [21].

In (8) and (7) reduce a big number of steps compared to algorithm of Chen’s [16] because before a flow \(f_i\) takes any value, the algorithm makes sure that this value can lead to a feasible solution by using (7). Utilizing these enhancements eliminates needless iterations, hence reducing the number of steps required to construct the flow vector \(F\).

4. RESULTS AND DISCUSSION

To test the efficiency between the new proposed improvements Chen’s [16] and Lin [21] algorithms, we used networks below taken from [16]. In Figure 2, we present the five grid networks for all three cases. All algorithms were programmed in C and executed on an HP computer with an Intel Core i7 processor of the second generation and 8 GB of RAM. Table 1 compares the algorithmic stages of Lin's [21], Chen's [16], and the suggested enhancements. Table 2 provides the execution times of the three methods in milliseconds. For all networks, the capabilities of all arcs equal five, and the demand \(d=5\). By adding in (8) and (7), it is evident from Tables 1 and 2 that the new adjustments reduced the number of steps and, therefore, the CPU time required by the algorithm to construct the vector flow \(F\).
Figure 2. Grid networks example with different nodes

Table 1. Comparison result between the 3 algorithms in terms of steps.

<table>
<thead>
<tr>
<th></th>
<th></th>
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<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>Graph a</td>
<td>1296</td>
<td>546</td>
<td>56</td>
</tr>
<tr>
<td>Graph b</td>
<td>279936</td>
<td>9726</td>
<td>462</td>
</tr>
<tr>
<td>Graph c</td>
<td>NA</td>
<td>573336</td>
<td>4368</td>
</tr>
<tr>
<td>Graph d</td>
<td>NA</td>
<td>121301496</td>
<td>65780</td>
</tr>
<tr>
<td>Graph e</td>
<td>NA</td>
<td>693876</td>
<td>11628</td>
</tr>
</tbody>
</table>

Table 2. The execution time of the 3 algorithms in ms.

<table>
<thead>
<tr>
<th></th>
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</thead>
<tbody>
<tr>
<td>Graph a</td>
<td>0.051 ms</td>
<td>0.009 ms</td>
<td>0.005 ms</td>
</tr>
<tr>
<td>Graph b</td>
<td>1.009 ms</td>
<td>0.11 ms</td>
<td>0.014 ms</td>
</tr>
<tr>
<td>Graph c</td>
<td>8821.56 ms</td>
<td>4.355 ms</td>
<td>0.205 ms</td>
</tr>
<tr>
<td>Graph d</td>
<td>NA ms</td>
<td>3573.58 ms</td>
<td>8.128 ms</td>
</tr>
<tr>
<td>Graph e</td>
<td>NA ms</td>
<td>15.867 ms</td>
<td></td>
</tr>
</tbody>
</table>

5. CONCLUSION

This study provides additional enhancements to Chen's method by taking full use of the constraints that locate the flow vector candidates. As a result, the number of steps required to enumerate the flow vector F is reduced by at least 60 times. Therefore, the amount of time it takes to execute. Lin's and Chen's algorithms were evaluated alongside the newly developed advancements. The findings of the tests indicate that the newly implemented improvements improved the effectiveness of discovering all d-MPs in multi-state networks for a given level d.

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**Yasser Lamalem** was born in Kenitra, Morocco. He received the master’s degree in computer science from Ibn Tofail University, in 2016, where he is currently pursuing the Ph.D. degree in network reliability. His current research interests include multi-state networks reliability and binary state networks reliability. He can be contacted at email: yasserlamalem@gmail.com.

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